

A brief introduction to Algebraic spaces

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The aim of this note is to give a brief introduction to Algebraic spaces. This note is based on the book [Alp25].

Contents

1	What is Algebraic Space?	1
2	Criteria for Algebraic Space	1
2.1	Representable of Diagonal	1
2.2	Algebraicity of Quotients by Groupoids	1
2.3	Characterization of Algebraic Spaces	2
3	Examples	2

1 What is Algebraic Space?**2 Criteria for Algebraic Space****2.1 Representable of Diagonal**

Theorem 1. (1) The diagonal of an algebraic space is representable by schemes.
 (2) The diagonal of an algebraic stack is representable.

Theorem 2. (1) If the diagonal of a stack \mathcal{X} is representable (resp., representable by a scheme), then every morphism $U \rightarrow \mathcal{X}$ from a scheme is representable (resp., representable by a scheme).
 (2) Every morphism from a scheme to an algebraic stack (resp., algebraic spaces) is representable (resp., representable by schemes).

2.2 Algebraicity of Quotients by Groupoids

Theorem 3. (1) If $R \rightrightarrows U$ is an étale (resp., smooth) groupoid of algebraic spaces. Then $[U/R]$ is a Deligne-Mumford stack (resp., algebraic stack) and $U \rightarrow [U/R]$ is an étale (resp., smooth) presentation.

(2) If $R \rightrightarrows U$ be an étale equivalence relation of schemes, then U/R is an algebraic space and $U \rightarrow U/R$ is an étale presentation.

Theorem 4. (1) If X is a sheaf on $\mathrm{Sch}_{\mathrm{et}}$ such that there exists a surjective, étale (resp., smooth), and representable morphism $U \rightarrow X$ from an algebraic space, then X is an algebraic space.
 (2) If $R \rightrightarrows U$ is an étale (resp. smooth) equivalence relation of algebraic spaces, then the quotient U/R is an algebraic space.

2.3 Characterization of Algebraic Spaces

Theorem 5. Let \mathcal{X} be an algebraic stack whose diagonal is representable by schemes. The following are equivalent:

- (1) the stack \mathcal{X} is an algebraic space,
- (2) the diagonal $\mathcal{X} \rightarrow \mathcal{X} \times \mathcal{X}$ is a monomorphism, and
- (3) every point of \mathcal{X} has a trivial stabilizer.

Theorem 6. For an algebraic stack \mathcal{X} , the following are equivalent:

- (1) the stack \mathcal{X} is an algebraic space,
- (2) the diagonal $\mathcal{X} \rightarrow \mathcal{X} \times \mathcal{X}$ is a monomorphism, and
- (3) every point of \mathcal{X} has a trivial stabilizer.

3 Examples

References

- [Alp25] J. Alper, *tacks and moduli*, 2025, <https://sites.math.washington.edu/~jarod/moduli.pdf>.